

# Chapter 1

## Introduction to Differential Equations

### Section 1.2

1. This D.E. is of order two because the highest derivative in the equation is  $y''$ .
2. Order is 1.
3. This D.E. is of order one because the highest derivative in the equation is  $y'$ . (Note:  $(y')^3 \neq y'''$ )
4. Order is 3.
5. Differentiating gives us  $y' = ke^{kt}$ . Substitution yields  $ke^{kt} + 2e^{kt} = 0$ . Therefore,  $k = -2$ .
6.  $y'' - y = 0 \Rightarrow k^2 e^{kt} - e^{kt} = 0 \Rightarrow k = \pm 1$ .
7. Differentiating gives us  $y' = -2k \sin 2te^{k \cos 2t}$ . Substitution yields  $-2k \sin 2te^{k \cos 2t} + \sin 2te^{k \cos 2t} = 0$ . Therefore,  $\sin 2te^{k \cos 2t}(-2k + 1) = 0$ , and solving for  $k$  gives us  $k = \frac{1}{2}$ .
8.  $y = ke^{-t}$ ,  $y' + y = 0$ ,  $-ke^{-t} + ke^{-t} = 0$ .  $k$  can be any real number.
- 9 (a).  $y = Ce^{t^2}$ . Differentiating gives us  $y' = Ce^{t^2} \cdot 2t = 2ty$ . Therefore,  $y' - 2ty = 0$  for any value of  $C$ .
- 9 (b). Substituting into the differential equation yields  $y(1) = Ce^{1^2} = Ce$ . Using the initial condition,  $y(1) = 2 = Ce$ . Solving for  $C$ , we find  $C = 2e^{-1}$ .
10.  $y''' = 2$ .  $y'' = 2t + c_1$ ,  $y' = t^2 + c_1t + c_2$ ,  $y = \frac{t^3}{3} + c_1 \frac{t^2}{2} + c_2t + c_3$ .  
Order = 3      3 arbitrary constants
- 11 (a).  $y = C_1 \sin 2t + C_2 \cos 2t$ . Differentiating gives us  $y' = 2C_1 \cos 2t - 2C_2 \sin 2t$  and  $y'' = -4C_1 \sin 2t - 4C_2 \cos 2t = -4(C_1 \sin 2t + C_2 \cos 2t) = -4y$ . Therefore,  $y'' + 4y = -4y + 4y = 0$  and thus  $y(t) = C_1 \sin 2t + C_2 \cos 2t$  is a solution of the D.E.  $y'' + 4y = 0$ .
- 11 (b).  $y\left(\frac{\pi}{4}\right) = C_1(1) + C_2(0) = C_1 = 3$  and  $y'\left(\frac{\pi}{4}\right) = 2C_1(0) - 2C_2(1) = -2C_2 = -2 \Rightarrow C_2 = 1$ .
12.  $y = 2e^{-4t}$ .  $y' + ky = -8e^{-4t} + 2ke^{-4t} = 2(k - 4)e^{-4t} = 0$   
 $\therefore k = 4$ .  $y(0) = 2 = y_0$ .  $\therefore k = 4, y_0 = 2$ .

13.  $y = ct^{-1}$ . Differentiating gives us  $y' = -ct^{-2}$ . Thus  $y' + y^2 = -ct^{-2} + c^2t^{-2} = (c^2 - c)t^{-2} = 0$ .  
Solving this for  $c$ , we find that  $c^2 - c = c(c - 1) = 0$ . Therefore,  $c = 0, 1$ .
14.  $y = -e^{-t} + \sin t$        $y' + y = g(t)$ ,  $y(0) = y_0$ .       $y' = e^{-t} + \cos t$   
 $y' + y = e^{-t} + \cos t - e^{-t} + \sin t = g$      $\therefore$      $g(t) = \cos t + \sin t$ ,  $y(0) = -1 = y_0$
15.  $y = t^r$ . Differentiating gives us  $y' = rt^{r-1}$  and  $y'' = r(r-1)t^{r-2}$ .  
Thus  $t^2y'' - 2ty' + 2y = r(r-1)t^r - 2rt^r + 2t^r = [r(r-1) - 2r + 2]t^r = 0$ . Solving this for  $r$ , we  
find that  $r(r-1) - 2r + 2 = r^2 - 3r + 2 = (r-2)(r-1) = 0$ . Therefore,  $r = 1, 2$ .
16.  $y = c_1e^{2t} + c_2e^{-2t}$ .     $y' = 2c_1e^{2t} - 2c_2e^{-2t}$ ,  $y'' = 4c_1e^{2t} + 4c_2e^{-2t} = 4y$   
 $\therefore$   $y'' - 4y = 0$ .
17. From (16),  $y = C_1e^{2t} + C_2e^{-2t}$ , which we differentiate to get  $y' = 2C_1e^{2t} - 2C_2e^{-2t}$ . Using the  
initial conditions,  $y(0) = 2$  and  $y'(0) = 0$ , we have two equations containing  $C_1$  and  $C_2$ :  
 $C_1 + C_2 = 2$  and  $2C_1 - 2C_2 = 0$ . Solving these simultaneous equations gives us  $C_1 = C_2 = 1$ . Thus,  
the solution to the initial value problem is  $y = e^{2t} + e^{-2t} = 2\cosh(2t)$ .
18.  $y(0) = c_1 + c_2 = 1$ ,  $2c_1 - 2c_2 = 2$      $\therefore$      $c_1 = 1$ ,  $c_2 = 0$      $y(t) = e^{2t}$ .
19. From (16),  $y(t) = C_1e^{2t} + C_2e^{-2t}$ . Using the initial condition  $y(0) = 3$ , we find that  $C_1 + C_2 = 3$ .  
From the initial condition  $\lim_{t \rightarrow \infty} y(t) = 0$  and the equation for  $y(t)$  given to us in (16), we can  
conclude that  $C_1 = 0$  (if  $C_1 \neq 0$ , then  $\lim_{t \rightarrow \infty} = \pm\infty$ ). Therefore,  $C_2 = 3$  and  $y(t) = 3e^{-2t}$ .
20.  $c_1 + c_2 = 10$      $\lim_{t \rightarrow -\infty} y(t) = 0 \Rightarrow c_2 = 0$      $\therefore$      $c_1 = 10$  and  $y(t) = 10e^{2t}$ .
21. From the graph, we can see that  $y' = -1$  and that  $y(1) = 1$ . Thus  $m = y' - 1 = -1 - 1 = -2$   
and  $y_0 = y(1) = 1$ .
22.  $y' = mt \Rightarrow y = \frac{m}{2}t^2 + c$ . From the graph,  $y = -1$  only at  $t = 0$      $\therefore$      $t_0 = 0$ .  
Also  $c = -1$ . From the graph  $y(1) = -0.5$      $\therefore$      $-\frac{1}{2} = \frac{m}{2} - 1 \Rightarrow m = 1$ .
23. We know that this is a freefall problem, so we can begin with the generic equation for freefall  
situations:  $y(t) = -\frac{g}{2}t^2 + v_0t + y_0$ . The object is released from rest, so  $v_0 = 0$ . The impact time  
corresponds to the time at which  $y = 0$ , so we are left with the following equation for the  
impact time  $t$ :  $0 = -\frac{g}{2}t^2 + y_0$ . Solving this for  $t$  yields  $t = \sqrt{\frac{2y_0}{g}}$ . For the velocity at the time of  
impact:  $v = y' = -gt + v_0 = -gt = -\sqrt{2gy_0}$ .

$$24. \quad x'' = a \quad x' = at + v_0, \quad v_0 = x_0 = 0 \Rightarrow x = \frac{at^2}{2} + 0.$$

$$88 = a(8) \Rightarrow a = 11 \text{ ft/sec}^2. \text{ At } t = 8, \quad x = 11\left(\frac{64}{2}\right) = 352 \text{ ft.}$$

### Section 1.3

- 1 (a). The equation is autonomous because  $y'$  depends only on  $y$ .
- 1 (b). Setting  $y' = 0$ , we have  $0 = -y + 1$ . Solving this for  $y$  yields the equilibrium solution:  $y = 1$ .
- 2 (a). not autonomous
- 2 (b). no equilibrium solutions, isoclines are  $t = \text{constant}$ .
- 3 (a). The equation is autonomous because  $y'$  depends only on  $y$ .
- 3 (b). Setting  $y' = 0$ , we have  $0 = \sin y$ . Solving this for  $y$  yields the equilibrium solutions:  $y = \pm n\pi$ .
- 4 (a). autonomous
- 4 (b).  $y(y - 1) = 0$ ,  $y = 0, 1$ .
- 5 (a). The equation is autonomous because  $y'$  does not depend explicitly on  $t$ .
- 5 (b). There are no equilibrium solutions because there are no points at which  $y' = 0$ .
- 6 (a). not autonomous
- 6 (b).  $y = 0$  is equilibrium solution, isoclines are hyperbolas.
- 7 (a).  $c = -1$ : Setting  $c = -1$  gives us  $-y + 1 = -1$  which, solved for  $y$ , reads  $y = 2$ . This is the isocline for  $c = -1$ .  
 $c = 0$ : Setting  $c = 0$  gives us  $-y + 1 = 0$  which, solved for  $y$ , reads  $y = 1$ . This is the isocline for  $c = 0$ .  
 $c = 1$ : Setting  $c = 1$  gives us  $-y + 1 = 1$  which, solved for  $y$ , reads  $y = 0$ , the isocline for  $c = 1$ .
- 8 (a).  $-y + t = -1 \Rightarrow y = t + 1$   
 $-y + t = 0 \Rightarrow y = t$   
 $-y + t = 1 \Rightarrow y = t - 1$
- 9 (a).  $c = -1$ : Setting  $c = -1$  gives us  $y^2 - t^2 = -1$  which can be simplified to  $t^2 - y^2 = 1$  (a hyperbola). This is the isocline for  $c = -1$ .  
 $c = 0$ : Setting  $c = 0$  gives us  $y^2 - t^2 = 0$  which can be simplified to  $y = \pm t$ . This is the isocline for  $c = 0$ .  
 $c = 1$ : Setting  $c = 1$  gives us  $y^2 - t^2 = 1$  (a hyperbola). This is the isocline for  $c = 1$ .

10.  $f(0) = f(2) = 0$   $y' = y(2 - y)$   
 $y' > 0$  for  $0 < y < 2$ ,  $y' < 0$  for  $-\infty < y < 0$  and  $2 < y < \infty$ .
11. One example that would fit these criteria is  $y' = -(y - 1)^2$ . For this autonomous D.E.,  $y' = 0$  at  $y = 1$  and  $y' < 0$  for  $-\infty < y < 1$  and  $1 < y < \infty$ .
12.  $y' = 1$ .
13. One example that would fit these criteria is  $y' = \sin(2\pi y)$ . For this autonomous D.E.,  
 $y' = 0$  at  $y = \frac{n}{2}$ .
14. c.
15. f.
16. a.
17. b.
18. d.
19. e.